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HiPeRT Ecosystem

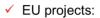
- High-Performance Real-Time Systems
- **Embedded AI**
- Autonomous Systems
 - 5 AD cars, LGV, delivery bots, aerial/(under)water drones
 - Autonomous racing: Indy Autonomous Challenge, F1/10, F SAE, Dallara F3
- ~80+ researchers/developers, 20+M€ funding

























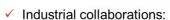


₩ P-SOCRATES





OPEN-NEXT



HERCULES



E XILINX



ARM































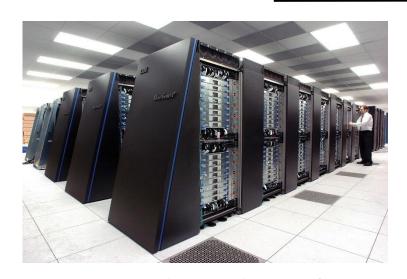




Embedding intelligence

2007:

IBM Blue Gene 200+ TFLOPS 131,000 CPUs 250 m2 1+MW (+ cooling)





2022: High-end embedded 200+ TOPS 40W

Scaling size of robotic controllers

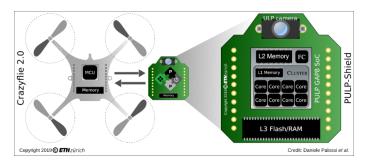






hercules2020.eu













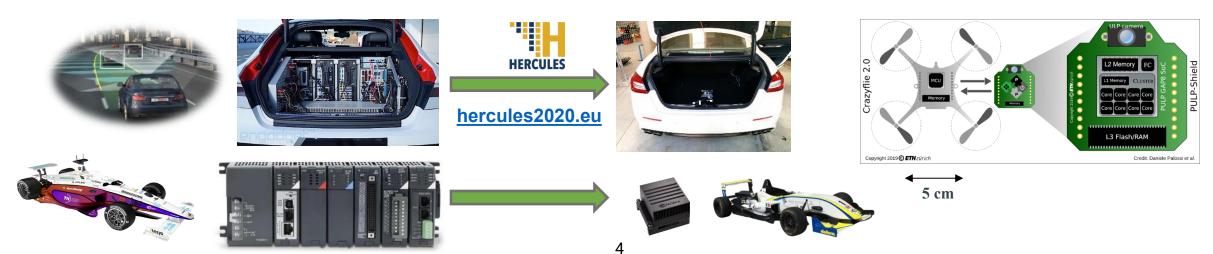
5 cm

Embedding intelligence

Everything that moves will be autonomous



Scaling size of robotic controllers



History of autonomous vehicles



THE ROAD TO FULL AUTOMATION

HISTORY OF AUTONOMOUS VEHICLES (AV) IN THE U.S.

1958

First car with cruise control is introduced

2004

DARPA Challenges are created to incentivize American autonomous vehicle development 2014

Google creates first AV prototype

2016

First known fatal accident involving a Tesla in autopilot mode. Other accidents followed.

2021

Ford and GM invest billions of dollars in AV technology and testing

1995

Carnegie Mellon University Navlab project completes cross-country trip with "semi-autonomous" vehicle

Graphic by: Sydney O'Shaughnessy Source: <u>Wikipedia, Reuters, The Verge</u> 2009

Google begins Self-Driving Car Project 2015

Tesla introduces autopilot software; University of Michigan's MCity AV Lab is launched 2018-20

AV mass transit programs debut in numerous states; NHTSA releases new AV guidance

An expensive challenge

The Self-Driving Car Companies Going The Distance

Number of autonomous test miles and miles per disengagement (Dec 2019-Nov 2020)*



^{*} Cases where a car's software detects a failure or a driver perceived a failure, resulting in control being seized by the driver.

Source: DMV California, via The Last Driver License Holder



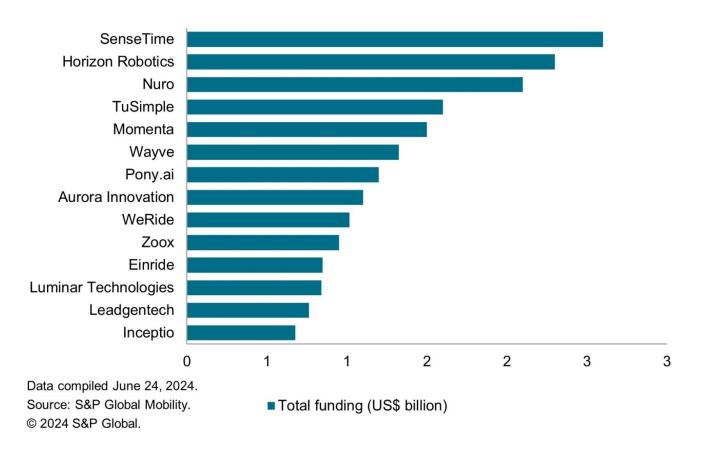






Top startups in autonomous driving domain

Global startups ranked by total funding received



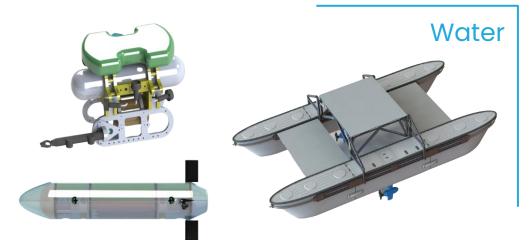


Autonomy as a Product and Service

Multiple robots and vehicles





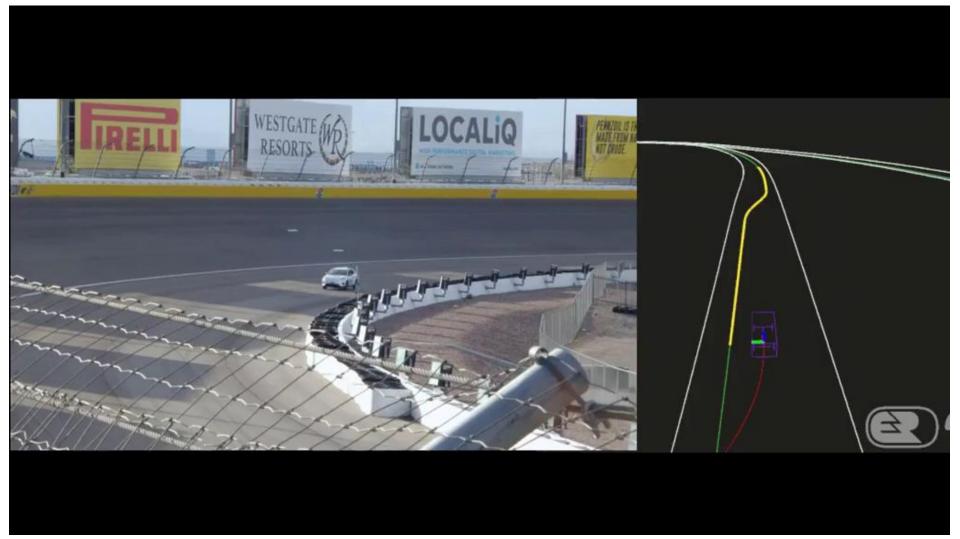








UNIMORE Racing team



07.01.2022 @ Las Vegas Motor Speeday

Top Speed: 272 kph

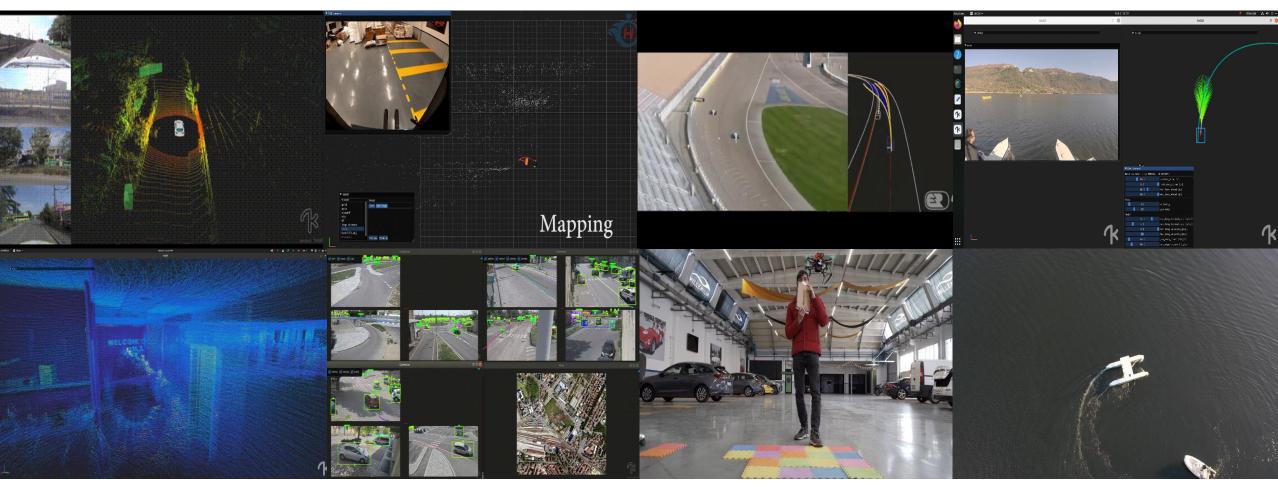
Top overtaking speed: 230 kph





One Platform, Multiple Domains

Sensor set, Embedded HPC, Software



Autonomous agriculture

Bulk spraying



Weed & Pest Control



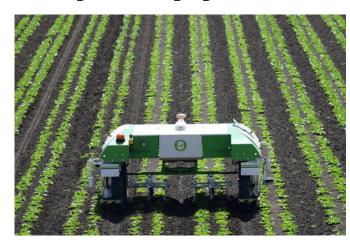
Monitoring, Field Mapping/Scouting



Autonomous tractor



Weeding & Seeding agriculture robot



Fruit-picking robot



Safe AD stack for agri

- Natural navigation in GPS-denied fields
- Safe obstacle detection/avoidance
- Sim before you go!
 - · Thousands of times...
- Easy-to-use HMI



Hipert's all terrain UGV

4 individually actuated tracks

4 actuated Links for improved flexibility

Electric powertrain

Long-range battery pack

Autonomous Sensing Kit/Platform



All terrain's UGV

Resilient to large obstacle

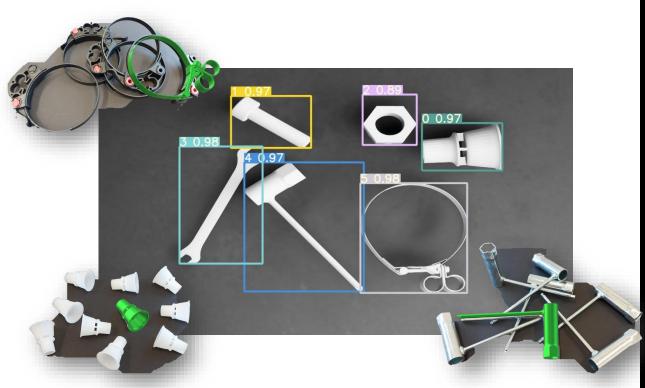






Dynamic Pick'n'Place

- Dynamic picking of objects in positions not known a priori Real-Time 6D pose estimation Planning and picking in-the-
- wild







From Steel to Code

Autonomous agriculture challenging classic business models

- Core value shifting from HW to SW
 - Anyone can build a robot, very few can make it operate safely in unstructured fields
 - · Hardware enables autonomy. Software *creates* autonomy.
- . HW reached a plateau, SW still scales (potentially exponentially)
 - Faster dev cycle, OTA, remote operation, data flywheel, retraining
 - Fast improvements in AI, perception, planning, control, HMI
 - Edge computing + Al allow real-time decision-making
- From demo to product is a long journey
 - The real barrier today isn't steel it's algorithms.
 - Way more difficult to fit SW functionalities for large scale products



Thank you!







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